Math 1D: Lesson 6 Suggested Problems

Theoretic Problems: Discussed in-class

- 1. Construct the cylindrical coordinate system in \mathbb{R}^3 from first principles. In particular:
 - A. Explain how to create a cylindrical coordinate system by extending the polar coordinate system from \mathbb{R}^2 into \mathbb{R}^3 . What are the similarities and differences between polar and cylindrical coordinates.
 - B. Starting from first principles and without looking back at your notes, create a description of each of the following objects in cylindrical coordinates: cylinder, cylindrical shell, vertical half plane, horizontal plane, cone.
 - C. Derive each of the formulas to convert from cartesian coordinates in \mathbb{R}^3 to cylindrical coordinates.
 - E. Derive each of the formulas to convert from cylindrical coordinates to cartesian coordinates in \mathbb{R}^3 .
- 2. Let $f: D \subseteq \mathbb{R}^3 \longrightarrow \mathbb{R}$ be a continuous function on a region D in \mathbb{R}^3 where D will be translated between cartesian coordinates and cylindrical coordinates.
 - A. Explain how to visualize the region

$$D = \left\{ (r, \theta, z) : \alpha \le \theta \le \beta, \ g(\theta) \le r \le h(\theta), \ G\left(r\cos(\theta), r\sin(\theta)\right) \le z \le H\left(r\cos(\theta), r\sin(\theta)\right) \right\}$$

in general. Specifically describe the meaning and effect of the functions $g(\theta), h(\theta), G(r\cos(\theta), r\sin(\theta))$ and $H(r\cos(\theta), r\sin(\theta))$

- B. Explain how to set up the uniform discretization (a regular partition) of D and how to enumerate subregions from k = 1, 2, ..., n.
- C. Explain how to choose a sample point $(r_k^*, \theta_k^*, z_k^*)$ from the kth subregion of the partition using the midpoint rule for the radial component.
- D. Explain how to translate the Riemann sum

$$\sum_{k=1}^n f(r_k^*, \theta_k^*, z_k^*) \ \Delta V_k$$

into the integral by taking a limit with respect to Δ where Δ is the maximum value of Δr , $\Delta \theta$ and Δz .

- E. Derive the formula for the volume of the kth sector of our partition as $\Delta V_k = r_k^* \cdot \Delta r \cdot \Delta \theta \Delta z$
- F. Using parts A E above, explain why the differential form dV used to measure "sizes" of points encoded in cylindrical coordinates has a factor of r in it where $dV = r \cdot dr \cdot d\theta \cdot dz$
- G. Now, explain why we define of the triple integral of our function f:

$$\iiint_D f(x,y,z) \ dV = \int_{\alpha}^{\beta} \int_{g(\theta)}^{h(\theta)} \int_{G}^{H} f(r,\theta,z) \ dz \ r \ dr \ d\theta$$

- 3. Construct the spherical coordinate system in \mathbb{R}^3 from first principles. In particular:
 - A. Explain how to create a spherical coordinate system in \mathbb{R}^3 . What are the similarities and differences between spherical and cylindrical coordinates.
 - B. Starting from first principles and without looking back at your notes, create a description of each of the following objects in spherical coordinates: sphere with radius ρ , a cone, vertical half plane, horizontal plane, cylinder.
 - C. Derive each of the formulas to convert from cartesian coordinates in \mathbb{R}^3 to spherical coordinates.
 - E. Derive each of the formulas to convert from spherical coordinates to cartesian coordinates in \mathbb{R}^3 .
- 4. Let $f: D \subseteq \mathbb{R}^3 \longrightarrow \mathbb{R}$ be a continuous function on a region D in \mathbb{R}^3 where D will be translated between cartesian coordinates and spherical coordinates.
 - A. Explain how to visualize the region

$$D = \{(\rho, \phi, \theta) : \alpha \le \theta \le \beta, \ a \le \phi \le b, \ g(\phi, \theta) \le \rho \le h(\phi, \theta)\}$$

in general. Specifically describe the meaning and effect of the functions $g(\phi, \theta)$ and $h(\phi, \theta)$.

- B. Explain how to set up the uniform discretization (a regular partition) of D and how to enumerate subregions from k = 1, 2, ..., n.
- C. Explain how to choose a sample point $(\rho_k^*, \phi_k^*, \theta_k^*)$ from the *k*th subregion of the partition using the midpoint rule for the radial component.
- D. Explain how to translate the Riemann sum

$$\sum_{k=1}^n f(\rho_k^*, \phi_k^*, \theta_k^*) \; \Delta V_k$$

into the integral by taking a limit with respect to Δ where Δ is the maximum of $\Delta \rho$, $\Delta \phi$ and $\Delta \theta$.

E. Derive the formula for the volume of the kth sector of our partition as

$$\Delta V_k \approx \left(\rho_k^*\right)^2 \cdot \sin(\phi_k) \ \Delta \rho \ \Delta \phi \ \Delta \theta$$

- F. Using parts A E above, explain why the differential form dV used to measure "sizes" of points encoded in spherical coordinates has a factor of $\rho^2 \sin(\phi)$ in it where $dV = \rho^2 \cdot \sin(\phi) d\rho \cdot d\phi \cdot d\theta$
- G. Now, explain why we define of the triple integral of our function f:

$$\iiint\limits_{D} f(x,y,z) \ dV = \int\limits_{\alpha}^{\beta} \int\limits_{a}^{b} \int\limits_{g(\phi,\theta)}^{h(\phi,\theta)} f(\rho,\phi,\theta) \ \rho^{2} \cdot \sin(\phi) \ d\rho \cdot d\phi \cdot d\theta$$

Problems Solved in Jeff's Handwritten Notes

- 3. Example 13.5.1 p.1008
- 4. Example 13.5.3 p. 1011 1012
- 5. Example 13.5.4 p. 1012 1013
- 6. Example 13.5.6 p. 1017 1018

Suggested Problems: Answers in Book

- 3. Exercise 13.5.9 p. 1019
- 4. Exercise 13.5.10 p. 1019
- 5. Exercise 13.5.21 p. 1019
- 6. Example 13.5.5 p. 1014
- 7. Exercise 13.5.39 p. 1020

Optional Challenge Problems

- 3. Exercise 13.5.75 p. 1022
- 4. Exercise 13.5.77 p. 1023
- 5. Exercise 13.5.78 p. 1023
- 6. Exercise 13.5.79 p. 1023
- 7. Exercise 13.5.80 p. 1023